

## CLAIMS

1           1.       (currently amended) A network-manager-implemented method, comprising:  
2           the network manager receiving one or more demands for service in a mesh network  
3 comprising a plurality of nodes interconnected by a plurality of links;  
4           the network manager specifying a threshold corresponding to a maximum number of failure-  
5 related cross-connections at a node in the network; and  
6           the network manager mapping each of the one or more demands onto a primary path and a  
7 restoration path in the network to generate a path plan for the one or more demands in the network,  
8 wherein:  
9                 reduction of a portion of restoration time associated with failure-related  
10 cross-connections in the network is taken into account during the mapping; [[and]]  
11                 the mapping generates the path plan based on the specified threshold such that, for  
12 all nodes in the mesh network, the number of failure-related cross-connections at each node is no  
13 more than the specified threshold; and  
14                 the mapping results in a maximum number of failure-related cross-connections at all  
15 nodes in the network being within a specified tolerance of a theoretical minimum.

1           2-3.    (canceled)

1           4.       (currently amended) The method of claim [[3]] 1, wherein a graph-theoretic  
2 condition is used to derive the theoretical minimum.

1           5.       (previously presented) The method of claim 4, wherein the theoretical minimum is  
2 defined by  $\max_{n \in N} \left\{ \lceil \delta_n / d_n \rceil \right\}$  where  $n$ , a node in the network, is an element of  $N$ , the set of all  
3 nodes in the network,  $\delta_n$  is the number of unit demands terminated on node  $n$ , and  $d_n$  is the  
4 number of edges incident on node  $n$ .

1           6.       (previously presented) The method of claim 1, wherein the mapping sequentially  
2 evaluates each possible path plan for each of the one or more demands and selects the path plan  
3 having a smallest maximum number of failure-related cross-connections.

1           7.       (previously presented) The method of claim 1, wherein the mapping comprises:  
2 selecting two node-disjoint paths for each demand, wherein leveling of link loads is taken  
3 into account during the selecting; and  
4 for each demand, identifying one of the two node-disjoint paths as the primary path and the  
5 other as the restoration path, wherein a maximum number of failure-related cross-connections at all  
6 nodes in the network is taken into account during the identifying.

1           8.       (currently amended) The method of claim 7, wherein:  
2 selecting the two node-disjoint paths for each demand minimizes maximum link bandwidth  
3 in the network; and  
4 identifying the primary and restoration paths for each demand results in the maximum  
5 number of failure-related cross-connections at all nodes in the network being within [[a]] the  
6 specified tolerance of [[a]] the theoretical minimum.

1           9.       (previously presented) The method of claim 8, wherein a tent pole condition is used  
2 to derive the theoretical minimum.

1           10.      (previously presented) The method of claim 7, wherein the selecting of the two  
2 node-disjoint paths for each demand and the identifying, for each demand, of the one of the two  
3 node-disjoint paths as the primary path and the other as the restoration path are implemented using  
4 mixed-integer programming.

1           11.      (previously presented) The method of claim 7, wherein the selecting of the two  
2 node-disjoint paths for each demand and the identifying, for each demand, of the one of the two  
3 node-disjoint paths as the primary path and the other as the restoration path are implemented using  
4 genetic programming.

1 12. (previously presented) The method of claim 7, wherein the selecting of the two  
2 node-disjoint paths for each demand and the identifying, for each demand, of the one of the two  
3 node-disjoint paths as the primary path and the other as the restoration path are implemented using  
4 a commercial solver.

1 13. (previously presented) The method of claim 1, wherein the mapping involves  
2 demand bundling, wherein demands having a common source node and a common destination node  
3 are grouped and routed along a single pair of disjoint primary and restoration paths and at least a  
4 portion of connection signaling for the group is carried out jointly.

1 14. (previously presented) The method of claim 1, wherein the mapping involves traffic  
2 aggregation, wherein multiple low-rate channels in the network are consolidated into a high-rate  
3 channel and rerouting of the high-rate channel requires fewer cross-connections than rerouting of  
4 the multiple low-rate channels.

1 15. (currently amended) A network manager for a mesh network comprising a plurality  
2 of nodes interconnected by a plurality of links, the network manager comprising:

3 means for receiving one or more demands for service in the network;

4 means for specifying a threshold corresponding to a maximum number of failure-related  
5 cross-connections at a node in the network; and

6 means for mapping each of the one or more demands onto a primary path and a restoration  
7 path in the network to generate a path plan for the one or more demands in the network, wherein:

8 reduction of a portion of restoration time associated with failure-related  
9 cross-connections in the network is taken into account during the mapping; [[and]]

10 the means for mapping generates the path plan based on the specified threshold such  
11 that, for all nodes in the mesh network, the number of failure-related cross-connections at each node  
12 is no more than the specified threshold; and

13 the path plan results in a maximum number of failure-related cross-connections at all  
14 nodes in the network being within a specified tolerance of a theoretical minimum.

1 16-17. (canceled)

1 18. (currently amended) The network manager of claim [[17]] 15, wherein a  
2 graph-theoretic condition is used to derive the theoretical minimum.

1 19. (previously presented) The network manager of claim 18, wherein the theoretical  
2 minimum is defined by:  $\max_{n \in N} \{ \lceil \delta_n / d_n \rceil \}$  where  $n$ , a node in the network, is an element of  $N$ ,  
3 the set of all nodes in the network,  $\delta_n$  is the number of unit demands terminated on node  $n$ , and  $d_n$   
4 is the number of edges incident on node  $n$ .

1 20. (previously presented) The network manager of claim 15, wherein the network  
2 manager comprises means for sequentially evaluating each possible path plan for each of the one or  
3 more demands and means for selecting the path plan having a smallest maximum number of  
4 failure-related cross-connections.

1 21. (previously presented) The network manager of claim 15, wherein the network  
2 manager comprises:  
3 means for performing selection of two node-disjoint paths for each demand, wherein  
4 leveling of link loads is taken into account during the selection; and  
5 means for identifying, for each demand, one of the two node-disjoint paths as the primary  
6 path and the other as the restoration path, wherein a maximum number of failure-related  
7 cross-connections at all nodes in the network is taken into account during the identifying.

1 22. (currently amended) The network manager of claim 21, wherein:  
2 the means for performing the selection of the two node-disjoint paths for each demand  
3 minimizes maximum link bandwidth in the network; and  
4 the means for identifying the primary and restoration paths for each demand results in the  
5 maximum number of failure-related cross-connections at all nodes in the network being within [[a]]  
6 the specified tolerance of [[a]] the theoretical minimum.

1           23.   (previously presented) The network manager of claim 22, wherein a tent pole  
2   condition is used to derive the theoretical minimum.

1           24.   (previously presented) The network manager of claim 21, wherein the means for  
2   performing the selection and the means for identifying the primary and restoration paths are  
3   implemented using mixed-integer programming.

1           25.   (previously presented) The network manager of claim 21, wherein the means for  
2   performing the selection and the means for identifying the primary and restoration paths are  
3   implemented using genetic programming.

1           26.   (previously presented) The network manager of claim 21, wherein the means for  
2   performing the selection and the means for identifying the primary and restoration paths are  
3   implemented using a commercial solver.

1           27.   (previously presented) The network manager of claim 15, wherein the network  
2   manager comprises means for considering demand bundling in the generation of the path plan,  
3   wherein demands having a common source node and a common destination node are grouped and  
4   routed along a single pair of disjoint primary and restoration paths and at least a portion of  
5   connection signaling for the group is carried out jointly.

1           28.   (previously presented) The network manager of claim 15, wherein the network  
2   manager comprises means for considering traffic aggregation in the generation of the path plan,  
3   wherein multiple low-rate channels in the network are consolidated into a high-rate channel and  
4   rerouting of the high-rate channel requires fewer cross-connections than rerouting of the multiple  
5   low-rate channels.

1           29-30. (canceled)

31. (new) A network-manager-implemented method, comprising:  
the network manager receiving one or more demands for service in a mesh network comprising a plurality of nodes interconnected by a plurality of links;  
the network manager specifying a threshold corresponding to a maximum number of failure-related cross-connections at a node in the network; and  
the network manager mapping each of the one or more demands onto a primary path and a restoration path in the network to generate a path plan for the one or more demands in the network, wherein:  
reduction of a portion of restoration time associated with failure-related cross-connections in the network is taken into account during the mapping;  
the mapping generates the path plan based on the specified threshold such that, for all nodes in the mesh network, the number of failure-related cross-connections at each node is no more than the specified threshold; and  
the mapping sequentially evaluates each possible path plan for each of the one or more demands and selects the path plan having a smallest maximum number of failure-related cross-connections.

32. (new) A network manager for a mesh network comprising a plurality of nodes interconnected by a plurality of links, the network manager comprising:  
means for receiving one or more demands for service in the network;  
means for specifying a threshold corresponding to a maximum number of failure-related cross-connections at a node in the network; and  
means for mapping each of the one or more demands onto a primary path and a restoration path in the network to generate a path plan for the one or more demands in the network, wherein:  
reduction of a portion of restoration time associated with failure-related cross-connections in the network is taken into account during the mapping;  
the means for mapping generates the path plan based on the specified threshold such that, for all nodes in the mesh network, the number of failure-related cross-connections at each node is no more than the specified threshold; and

13                   the network manager comprises means for sequentially evaluating each possible path  
14   plan for each of the one or more demands and means for selecting the path plan having a smallest  
15   maximum number of failure-related cross-connections.